Assignment: A15 (help)

Air-Table: Final features

The following two images highlight the changes that need to be made to the "Spring" class to support the pinned-spring feature.

```
class Spring:
def init (self, p1, p2, length m=3.0, strength Npm=0.5, spring color=THECOLORS["yellow"], width m=0.025, drag c=0.0):
    # Optionally this spring can have one end pinned to a vector point. Do this by passing in p2 as a vector.
    # The location of this point puck will never change because
       # it is not in the pucks list that is processed by the
       # physics engine.
       p2 = Puck( p2, 1.0, 1.0)
       p2.vel 2d mps = Vec2D(0.0,0.0)
       length_m = 0.0
    self.p1 = p1
    self.p2 = p2
    self.p1p2_separation_2d_m = Vec2D(0,0)
    self.p1p2_separation_m = 0
    self.p1p2_normalized_2d = Vec2D(0,0)
    {\tt self.length\_m = length\_m}
    self.strength Npm = strength Npm
    self.damper_Ns2pm2 = 0.5 #5.0 #0.05 #0.15
    self.unstretched_width_m = width_m #0.05
   self.drag_c = drag_c
    self.spring_vertices_2d_m = []
    self.spring vertices 2d px = []
    self.spring_color = spring_color
    self.draw_as_line = False
```

```
def calc spring forces on pucks(self):
self.p1p2_separation_2d_m = self.p1.pos_2d_m - self.p2.pos_2d_m
self.p1p2_separation_m = self.p1p2_separation_2d_m.length()
# The pinned case needs to be able to handle the zero length spring. The
# separation distance will be zero when the pinned spring is at rest.
# This will cause a divide by zero error if not handled here.
if ((self.p1p2 separation m == 0.0) and (self.length m == 0.0)):
    spring_force_on_1_2d_N = Vec2D(0.0,0.0)
    self.p1p2_normalized_2d = self.p1p2_separation_2d_m / self.p1p2_separation_m
    # Spring force: acts along the separation vector and is proportional to the separation distance.
    spring_force_on_1_2d_N = self.p1p2_normalized_2d * (self.length_m - self.p1p2_separation_m) * self.strength_Npm
# Damper force: acts along the separation vector and is proportional to the relative speed.
v_relative_2d_mps = self.p1.vel_2d_mps - self.p2.vel_2d_mps
v relative alongNormal 2d mps = v relative 2d mps.projection onto(self.p1p2 separation 2d m)
damper_force_on_1_N = v_relative_alongNormal_2d_mps * self.damper_Ns2pm2
# Net force by both spring and damper
SprDamp_force_2d_N = spring_force_on_1_2d_N - damper_force_on_1_N
# This force acts in opposite directions for each of the two pucks. Notice the "+=" here, this
# is an aggregate across all the springs. This aggregate MUST be reset (zeroed) after the movements are
# calculated. So by the time you've looped through all the springs, you get the NET force, one each ball,
# applied of all individual springs.
self.pl.SprDamp_force_2d_N += SprDamp_force_2d_N * (+1)
self.p2.SprDamp_force_2d_N += SprDamp_force_2d_N * (-1)
# Add in some drag forces if a non-zero drag coef is specified. These are based on the
# velocity of the pucks (not relative speed as is the case above for damper forces).
self.pl.SprDamp force 2d N += self.pl.vel 2d mps * (-1) * self.drag c
self.p2.SprDamp_force_2d_N += self.p2.vel_2d_mps * (-1) * self.drag_c
```